

The z-Transform

✧ Introduction

- Why do we study them?
 - A generalization of DTFT.
 - Some sequences that do not converge for DTFT have valid z-transforms.
 - Better notation (compared to FT) in analytical problems (complex variable theory)
 - Solving difference equation. → algebraic equation.

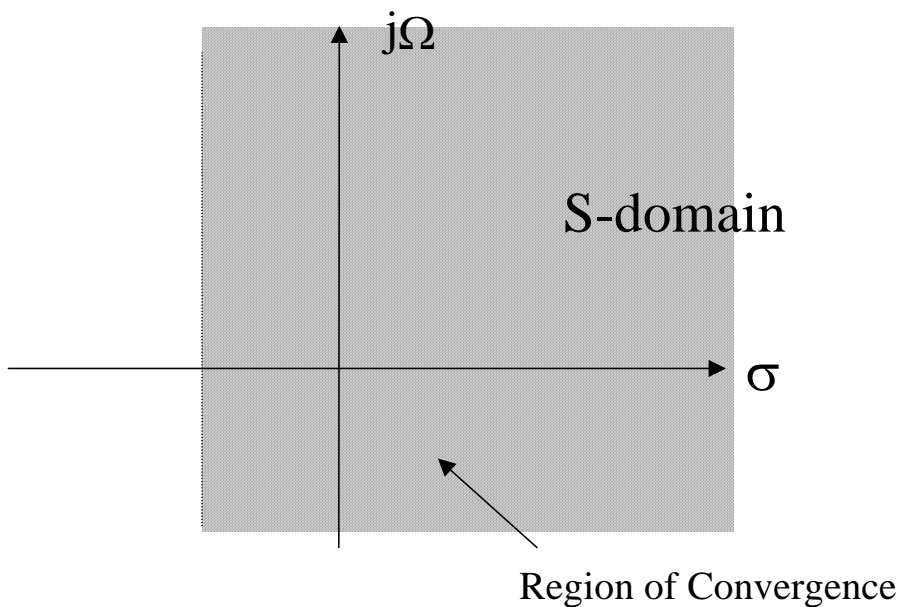
- **Fourier Transform, Laplace Transform, DTFT, & z-Transform**

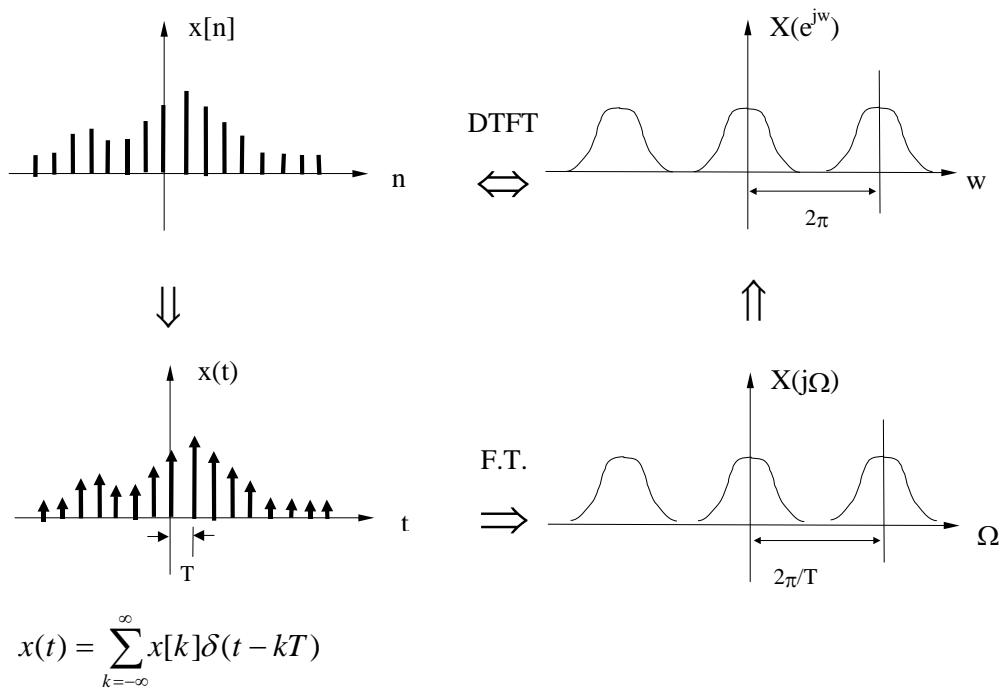
Fourier Transform

$$\mathfrak{F}\{x(t)\} = \int_{-\infty}^{\infty} x(t)e^{-j\Omega t} dt$$

To encompass a broader class of signals:

$$\int_{-\infty}^{\infty} (x(t)e^{-\sigma t})e^{-j\Omega t} dt \equiv \int_{-\infty}^{\infty} x(t)e^{-st} dt \equiv L\{x(t)\} \quad \text{Laplace Transform}$$



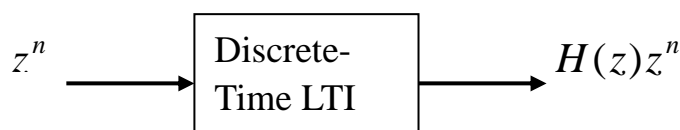


Similarly,

$$\begin{aligned}
 L\{x(t)\} &= L\left\{\sum_{k=-\infty}^{\infty} x[k] \delta(t - kT)\right\} = \int_{-\infty}^{\infty} \left\{\sum_{k=-\infty}^{\infty} x[k] \delta(t - kT)\right\} e^{-st} dt = \sum_{k=-\infty}^{\infty} x[k] \int_{-\infty}^{\infty} \delta(t - kT) e^{-st} dt \\
 &= \sum_{k=-\infty}^{\infty} x[k] e^{-skT} \equiv \sum_{k=-\infty}^{\infty} x[k] z^{-k} \equiv Z\{x[n]\} \equiv X(z)
 \end{aligned}$$

z-Transform

● Eigenfunctions of discrete-time LTI systems



If $x[n] = z_0^n$ z_0^n : some complex constant

$$y[n] = x[n] * h[n] = \sum_{k=-\infty}^{\infty} x[n-k] h[k] = \sum_{k=-\infty}^{\infty} z_0^{n-k} h[k] = \left\{ \sum_{k=-\infty}^{\infty} h[k] z_0^{-k} \right\} z_0^n = H(z_0) z_0^n$$

Remark:

$$X(z) \Big|_{z=e^{j\omega}} = \sum_{n=-\infty}^{\infty} x[n] e^{-jn\omega}$$

DTFT can be viewed as a special case: $z = e^{j\omega}$

✧ z-Transform

- (Two-sided) z-Transform (bilateral z-Transform)

Forward: $Z\{x[n]\} = \sum_{n=-\infty}^{\infty} x[n]z^{-n} \equiv X(z)$

From DTFT viewpoint: $Z\{x[n]\} = F\{r^{-n}x[n]\}|_{re^{j\omega}=z}$

(Or, DTFT is a special case of z-T when $z = e^{j\omega}$, *unit circle*.)

Inverse: $x[n] = \frac{1}{2\pi j} \oint_{\Gamma} X(z)z^{n-1}dz \equiv Z^{-1}[X(z)]$

Note: The integration is evaluated along a counterclockwise circle on the complex z plane with a radius r . (A proof of this formula requires the complex variable theory.)

- **Single-sided z-Transform** (unilateral) – for causal sequences

$$X(z) = \sum_{n=0}^{\infty} x[n]z^{-n}$$

- **Region of Convergence (ROC)**

The set of values of z for which the z -transform converges.

- *Uniform convergence*

If $z = re^{j\omega}$ (polar form), the z -transform converges uniformly if $x[n]r^{-n}$ is *absolutely summable*; that is,

$$\sum_{n=-\infty}^{\infty} |x[n]r^{-n}| < \infty$$

- In general, if some value of z , say $z = z_1$, is in the ROC, then all values of z on the circle defined by $|z| = |z_1|$ are also in the ROC. → ROC is a “ring”.
 - If ROC contains the unit circle, $|z| = 1$, then the FT of this sequence converges.
 - By its definition, $X(z)$ is a Laurent series (complex variable)
 - $X(z)$ is an *analytic function* in its ROC
 - All its derivatives are continuous (in z) within its ROC.

■ DTFT v.s. z-Transform

-- $x_1[n] = \frac{\sin \omega_c n}{\pi}, \quad -\infty < n < \infty$

Not absolutely summable; but square summable

→ z-transform does not exist; DTFT (in m.s. sense) exists.

-- $x_2[n] = \cos \omega_0 n, \quad -\infty < n < \infty$

Not absolutely summable; not square summable

→ z-transform does not exist; “useful” DTFT (impulses) exists.

-- $x_3[n] = a^n u[n], \quad |a| > 1, \quad -\infty < n < \infty$

→ z-transform exist (a certain ROC); DTFT does not exists.

● Some Common Z-T Pairs

■ $\delta[n] \leftrightarrow 1, \delta[n - m] \leftrightarrow z^{-m}, \quad m > 0, |z| > 0,$

$\delta[n + m] \leftrightarrow z^m, \quad m > 0, |z| < \infty$

■ $u[n] \leftrightarrow \frac{1}{1 - z^{-1}}, \quad |z| > 1, -u[-n - 1] \leftrightarrow \frac{1}{1 - z^{-1}}, \quad |z| < 1$

■ $a^n u[n] \leftrightarrow \frac{1}{1 - az^{-1}}, \quad |z| > |a|,$

$-a^n u[-n - 1] \leftrightarrow \frac{1}{1 - az^{-1}}, \quad |z| < |a|$

■ $r^n \cos[\omega_0 n] u[n] \leftrightarrow \frac{1 - [r \cos \omega_0] z^{-1}}{1 - [2r \cos \omega_0] z^{-1} + r^2 z^{-2}}, |z| > r$

$r^n \sin[\omega_0 n] u[n] \leftrightarrow \frac{1 - [r \sin \omega_0] z^{-1}}{1 - [2r \sin \omega_0] z^{-1} + r^2 z^{-2}}, |z| > r$

✧ Properties of ROC for z-Transform

● Rational functions

$$X(z) = \frac{P(z)}{Q(z)}$$

Poles – Roots of the denominator; the z such that $X(z) \rightarrow \infty$

Zeros – Roots of the numerator; the z such that $X(z) = 0$

■ Properties of ROC

- (1) The ROC is a ring or disk in the z -plane centered at the origin.
- (2) The F.T. of $x[n]$ converges absolutely \Leftrightarrow its ROC includes the unit circle.
- (3) The ROC cannot contain any poles.
- (4) If $x[n]$ is *finite-duration*, then the ROC is the entire z -plane except possibly $z = 0$ or $z = \infty$.
- (5) If $x[n]$ is *right-sided*, the ROC, if exists, must be of the form $|z| > r_{\max}$ except possibly $z = \infty$, where r_{\max} is the magnitude of the largest pole.
- (6) If $x[n]$ is *left-sided*, the ROC, if exists, must be of the form $|z| < r_{\min}$ except possibly $z = 0$, where r_{\min} is the magnitude of the smallest pole.
- (7) If $x[n]$ is *two-sided*, the ROC must be of the form $r_1 < |z| < r_2$ if exists, where r_1 and r_2 are the magnitudes of the interior and exterior poles.
- (8) The ROC must be a connected region.

In general, if $X(z)$ is rational, its inverse has the following form (assuming N poles: $\{d_k\}$)

$x[n] = \sum_{k=1}^N A_k (d_k)^n$. For a right-sided sequence, it means $n \geq N_1$, where N_1 is the first nonzero sample.

The n th term in the z -transform is $x[n]r^{-n} = \sum_{k=1}^N A_k (d_k r^{-1})^n$.

This sequence converges if $\sum_{n=N_1}^{\infty} |d_k r^{-1}|^n < \infty$ for every pole $k = 1, \dots, N$. In order to

be so, $|r| > |d_k|$, $k = 1, \dots, N$.

✧ Pole Location and Time-Domain Behavior for Causal Signals

Reference: Digital Signal Processing by Proakis & Manolakis

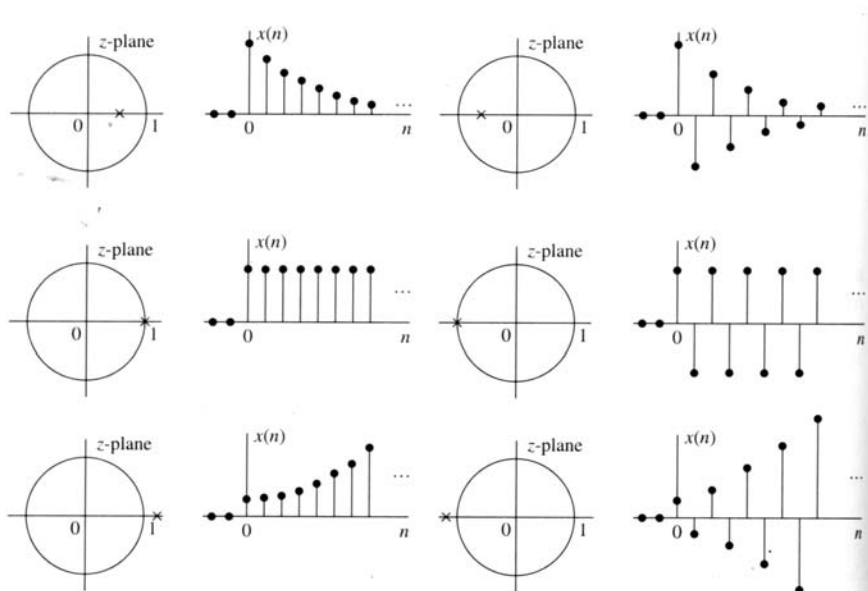


Figure 3.11 Time-domain behavior of a single-real pole causal signal as a function of the location of the pole with respect to the unit circle.

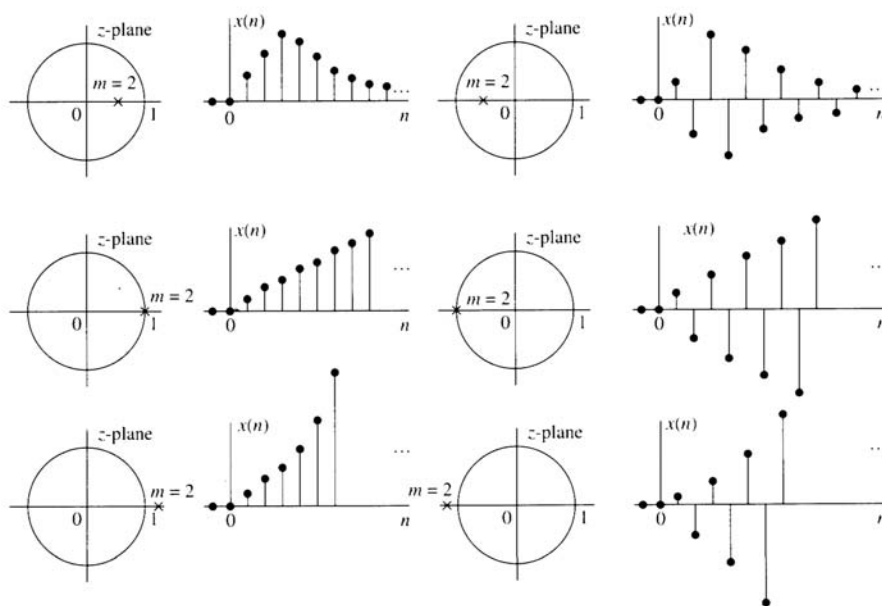


Figure 3.12 Time-domain behavior of causal signals corresponding to a double ($m = 2$) real pole, as a function of the pole location.

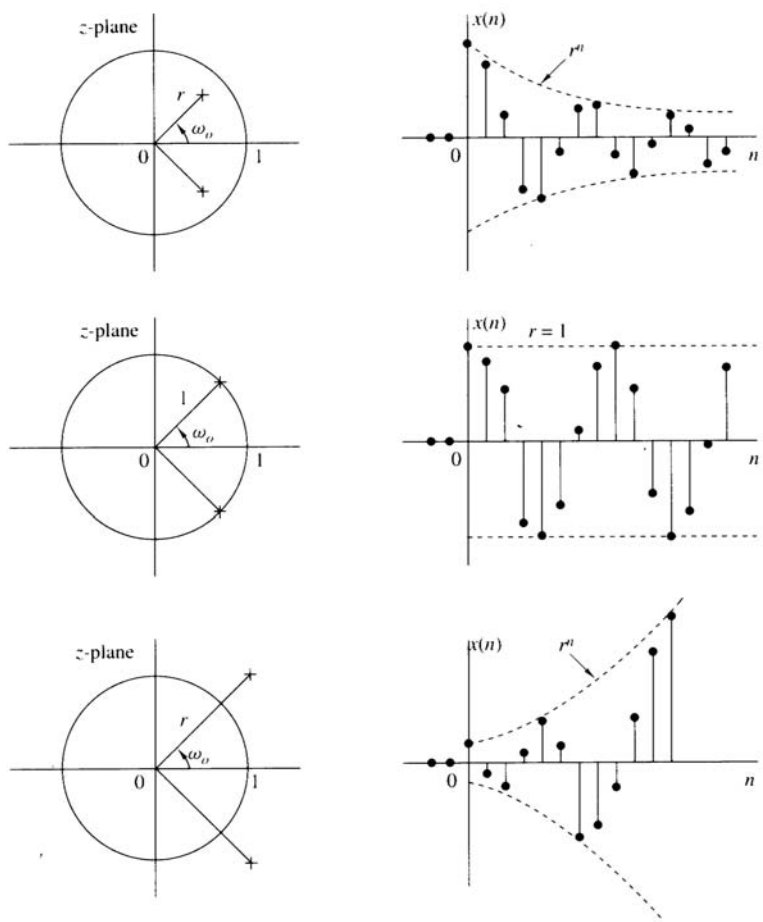


Figure 3.13 A pair of complex-conjugate poles corresponds to causal signals with oscillatory behavior.

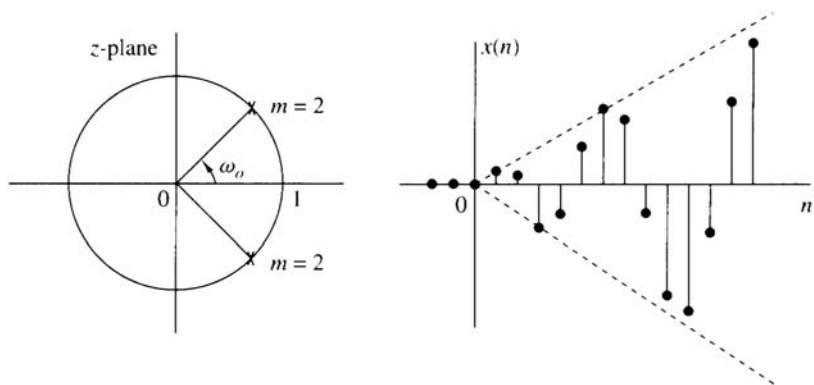


Figure 3.14 Causal signal corresponding to a double pair of complex-conjugate poles on the unit circle.

✧ The Inverse z-Transform

Inverse formula: $x[n] = \frac{1}{2\pi j} \oint_{\Gamma} X(z)z^{n-1} dz$

This formula can be proved using Cauchy integral theorem (complex variable theory).

- Methods of evaluating the inverse z-transform
 - (1) Table lookup or inspection
 - (2) Partial fraction expansion
 - (3) Power series expansion
- **Inspection** (transform pairs in the table) – memorized them
- **Partial Fraction Expansion**

$$X(z) = \frac{b_0 + b_1 z^{-1} + \dots + b_M z^{-M}}{a_0 + a_1 z^{-1} + \dots + a_N z^{-N}} \rightarrow X(z) = \frac{z^N (b_0 z^M + \dots + b_M)}{z^M (a_0 z^N + \dots + a_N)}$$

Hence, it has M zeros (roots of $\sum b_k z^{M-k}$), N poles (roots of $\sum a_k z^{N-k}$), and $(M-N)$ poles at zero if $M > N$ (or $(N-M)$ zeros at zero if $N > M$).

$$\rightarrow X(z) = \frac{b_0(1 - c_1 z^{-1}) \dots (1 - c_M z^{-1})}{a_0(1 - d_1 z^{-1}) \dots (1 - d_N z^{-1})}; \quad c_k, \text{ nonzero zeros}; \quad d_k, \text{ nonzero poles.}$$

■ **Case 1:** $M < N$, strictly proper

Simple (single) poles:

$$X(z) = \frac{A_1}{(1 - d_1 z^{-1})} + \frac{A_2}{(1 - d_2 z^{-1})} + \dots + \frac{A_N}{(1 - d_N z^{-1})}$$

where $A_k = (1 - d_k z^{-1})X(z)|_{z=d_k}$

Multiple poles: Assume d_i is the s th order pole. (Repeated s times)

$$X(z) = \sum_{k=1, k \neq i}^N \frac{A_k}{(1 - d_k z^{-1})} + \frac{C_1}{(1 - d_i z^{-1})} + \frac{C_2}{(1 - d_i z^{-1})^2} + \dots + \frac{C_s}{(1 - d_i z^{-1})^s}$$

single-pole terms
multiple-pole terms

where $C_m = \frac{1}{(s-m)!(-d_i)^{s-m}} \left\{ \frac{d^{s-m}}{dw^{s-m}} [(1 - d_i w)^s X(w^{-1})] \right\}_{w=d_i^{-1}}$

■ **Case 2:** $M \geq N$

$$X(z) = \sum_{r=0}^{M-N} B_r z^{-r} + \sum_{k=1, k \neq i}^N \frac{A_k}{(1 - d_k z^{-1})} + \sum_{m=1}^s \frac{C_m}{(1 - d_i z^{-1})^m}$$

impulses single-poles multiple-pole

● **Power Series Expansion**

$$X(z) = \sum_{n=-\infty}^{\infty} x[n]z^{-n}$$

- Case 1: Right-sided sequence, ROC: $|z| > r_{\max}$

It is expanded in powers of z^{-1} .

Ex. $X(z) = \frac{1}{1-az^{-1}}, \quad |z| > |a|$

- Case 2: Left-sided sequence, ROC: $|z| < r_{\min}$

It is expanded in powers of z .

Ex. $X(z) = \frac{1}{1-az^{-1}}, \quad |z| < |a|$

- Case 3: Two-sided sequence, ROC: $r_1 < |z| < r_2$

$$X(z) = X_+(z) + X_-(z)$$

converges for $|z| > r_1$ converges for $|z| < r_2$

$$\rightarrow x[n] = x_+[n] + x_-[n]$$

causal sequence anti-causal sequence

✧ z-Transform Properties

If $x[n] \leftrightarrow X[z]$ and $y[n] \leftrightarrow Y[z]$, ROC: R_X, R_Y

■ **Linearity:** $ax[n] + by[n] \leftrightarrow aX(z) + bY(z)$

ROC: $R' \supset R_X \cap R_Y$ -- At least as large as their intersection; larger if pole/zero cancellation occurs

■ **Time Shifting:** $x[n - n_0] \leftrightarrow z^{-n_0} X(z)$ ROC: $R' = R_X \pm \{0 \text{ or } \infty\}$

■ **Multiplication by an exponential sequence:**

$a^n x[n] \leftrightarrow X(z/a)$ ROC: $R' = |a|R_X$ -- expands or contracts

■ **Differentiation of X(z):** $nx[n] \leftrightarrow -z \frac{dX(z)}{dz}$, ROC: $R' = R_X$

■ **Conjugation of a complex sequence:** $x^*[n] \leftrightarrow X^*(z^*)$, ROC: $R' = R_X$

■ **Time reversal:** $x^*[-n] \leftrightarrow X^*(1/z^*)$,

ROC: $R' = 1/R_X$ (Meaning: If $R_X : r_R < |z| < r_L$, then $R' : 1/r_L < |z| < 1/r_R$.)

Corollary: $x[-n] \leftrightarrow X(1/z)$

■ **Convolution:** $x[n] * y[n] \leftrightarrow X(z)Y(z)$

ROC: $R' \supset R_X \cap R_Y$ (=, if no pole/zero cancellation)

■ **Initial Value Theorem:**

If $x[n]=0, n<0$, then $x[0] = \lim_{z \rightarrow \infty} X(z)$

■ **Final Value Theorem:**

If (1) $x[n]=0, n<0$, and

(2) all singularities of $(1 - z^{-1})X(z)$ are inside the unit circle,

then $x[\infty] = \lim_{z \rightarrow 1} (1 - z^{-1})X(z)$

Remarks: (1) If all poles of $X(z)$ are inside unit circle, $x[n] \rightarrow 0$ as $n \rightarrow \infty$

(2) If there are multiple poles at “1”, $x[n] \rightarrow \infty$ as $n \rightarrow \infty$

(3) If poles are on the unit circle but not at “1”, $x[n] \approx \cos \omega_0 n$

<Supplementary>

z-Transform Solutions of Linear Difference Equations

Use *single-sided* z-transform:

$$Z\{y[n-1]\} = z^{-1}Y(z) + y[-1]$$

$$Z\{y[n-2]\} = z^{-2}Y(z) + z^{-1}y[-1] + y[-2]$$

$$Z\{y[n-3]\} = z^{-3}Y(z) + z^{-2}y[-1] + z^{-1}y[-2] + y[-3]$$

For causal signals, their single-sided z-transforms are identical to their two-sided z-transforms.

Ex., Find $y[n]$ of the difference eqn.

$$y[n] - 0.5y[n-1] = x[n] \quad \text{with } x[n] = 1, n \geq 0, \text{ and } y[-1] = 1$$

(Sol) Take the single-sided z-transform of the above eqn.

$$\rightarrow Y(z) - 0.5\{z^{-1}Y(z) + y[-1]\} = X(z) = \frac{1}{1-z^{-1}}$$

$$\begin{aligned} \rightarrow Y(z) &= \left\{ \frac{1}{1-0.5z^{-1}} \right\} \left\{ 0.5 + \frac{1}{1-z^{-1}} \right\} \\ &= \frac{0.5}{1-0.5z^{-1}} + \frac{1}{(1-0.5z^{-1})(1-z^{-1})} \end{aligned}$$

$$\rightarrow Y(z) = \frac{2}{1-z^{-1}} - \frac{0.5}{1-0.5z^{-1}}$$

Take the inverse z-transform

$$\rightarrow y[n] = 2 - 0.5(0.5)^n, \quad n \geq 0$$