

# Chapter 1

## Introduction to Differential Equations

### Section 1.1

1. This D.E. is of order two because the highest derivative in the equation is  $y''$ .
2. Order is 1.
3. This D.E. is of order one because the highest derivative in the equation is  $y'$ . (Note:  $(y')^3 \neq y'''$ )
4. Order is 3.
- 5 (a).  $y = Ce^{t^2}$ . Differentiating gives us  $y' = Ce^{t^2} \cdot 2t = 2ty$ . Therefore,  $y' - 2ty = 0$  for any value of  $C$ .
- 5 (b). Substituting into the differential equation yields  $y(1) = Ce^{1^2} = Ce$ . Using the initial condition,  $y(1) = 2 = Ce$ . Solving for  $C$ , we find  $C = 2e^{-1}$ .
6.  $y''' = 2$ .  $y'' = 2t + c_1$ ,  $y' = t^2 + c_1t + c_2$ ,  $y = \frac{t^3}{3} + c_1 \frac{t^2}{2} + c_2t + c_3$ .  
Order = 3      3 arbitrary constants
- 7 (a).  $y = C_1 \sin 2t + C_2 \cos 2t$ . Differentiating gives us  $y' = 2C_1 \cos 2t - 2C_2 \sin 2t$  and  $y'' = -4C_1 \sin 2t - 4C_2 \cos 2t = -4(C_1 \sin 2t + C_2 \cos 2t) = -4y$ . Therefore,  $y'' + 4y = -4y + 4y = 0$  and thus  $y(t) = C_1 \sin 2t + C_2 \cos 2t$  is a solution of the D.E.  
 $y'' + 4y = 0$ .
- 7 (b).  $y(\frac{\pi}{4}) = C_1(1) + C_2(0) = C_1 = 3$  and  $y'(\frac{\pi}{4}) = 2C_1(0) - 2C_2(1) = -2C_2 = -2 \Rightarrow C_2 = 1$ .
8.  $y = 2e^{-4t}$ .  $y' + ky = -8e^{-4t} + 2ke^{-4t} = 2(k-4)e^{-4t} = 0$   
 $\therefore k = 4$ .  $y(0) = 2 = y_0$ .  $\therefore k = 4, y_0 = 2$ .
9.  $y = ct^{-1}$ . Differentiating gives us  $y' = -ct^{-2}$ . Thus  $y' + y^2 = -ct^{-2} + c^2t^{-2} = (c^2 - c)t^{-2} = 0$ .  
Solving this for  $c$ , we find that  $c^2 - c = c(c-1) = 0$ . Therefore,  $c = 0, 1$ .
10.  $y = -e^{-t} + \sin t$        $y' + y = g(t)$ ,  $y(0) = y_0$ .       $y' = e^{-t} + \cos t$   
 $y' + y = e^{-t} + \cos t - e^{-t} + \sin t = g$        $\therefore g(t) = \cos t + \sin t$ ,  $y(0) = -1 = y_0$

11.  $y = t^r$ . Differentiating gives us  $y' = rt^{r-1}$  and  $y'' = r(r-1)t^{r-2}$ . Thus  $t^2 y'' - 2ty' + 2y = r(r-1)t^r - 2rt^r + 2t^r = [r(r-1) - 2r + 2]t^r = 0$ . Solving this for  $r$ , we find that  $r(r-1) - 2r + 2 = r^2 - 3r + 2 = (r-2)(r-1) = 0$ . Therefore,  $r = 1, 2$ .
12.  $y = c_1 e^{2t} + c_2 e^{-2t}$ .  $y' = 2c_1 e^{2t} - 2c_2 e^{-2t}$ ,  $y'' = 4c_1 e^{2t} + 4c_2 e^{-2t} = 4y$   
 $\therefore y'' - 4y = 0$ .
13. From (12),  $y = C_1 e^{2t} + C_2 e^{-2t}$ , which we differentiate to get  $y' = 2C_1 e^{2t} - 2C_2 e^{-2t}$ . Using the initial conditions,  $y(0) = 2$  and  $y'(0) = 0$ , we have two equations containing  $C_1$  and  $C_2$ :  $C_1 + C_2 = 2$  and  $2C_1 - 2C_2 = 0$ . Solving these simultaneous equations gives us  $C_1 = C_2 = 1$ . Thus, the solution to the initial value problem is  $y = e^{2t} + e^{-2t} = 2 \cosh(2t)$ .
14.  $y(0) = c_1 + c_2 = 1$ ,  $2c_1 - 2c_2 = 2 \quad \therefore c_1 = 1, c_2 = 0 \quad y(t) = e^{2t}$ .
15. From (12),  $y(t) = C_1 e^{2t} + C_2 e^{-2t}$ . Using the initial condition  $y(0) = 3$ , we find that  $C_1 + C_2 = 3$ . From the initial condition  $\lim_{t \rightarrow \infty} y(t) = 0$  and the equation for  $y(t)$  given to us in (12), we can conclude that  $C_1 = 0$  (if  $C_1 \neq 0$ , then  $\lim_{t \rightarrow \infty} = \pm\infty$ ). Therefore,  $C_2 = 3$  and  $y(t) = 3e^{-2t}$ .
16.  $c_1 + c_2 = 10 \quad \lim_{t \rightarrow -\infty} y(t) = 0 \Rightarrow c_2 = 0 \quad \therefore c_1 = 10 \text{ \& } y(t) = 10e^{2t}$ .
17. From the graph, we can see that  $y' = -1$  and that  $y(1) = 1$ . Thus  $m = y' - 1 = -1 - 1 = -2$  and  $y_0 = y(1) = 1$ .
18.  $y' = mt \Rightarrow y = \frac{m}{2} t^2 + c$ . From graph,  $y = -1$  only at  $t = 0 \quad \therefore t_0 = 0$ .  
 Also  $c = -1$ . From graph  $y(1) = -0.5 \quad \therefore -\frac{1}{2} = \frac{m}{2} - 1 \Rightarrow m = 1$ .
19. We know that this is a freefall problem, so we can begin with the generic equation for freefall situations:  $y(t) = -\frac{g}{2} t^2 + v_0 t + y_0$ . The object is released from rest, so  $v_0 = 0$ . The impact time corresponds to the time at which  $y = 0$ , so we are left with the following equation for the impact time  $t$ :  $0 = -\frac{g}{2} t^2 + y_0$ . Solving this for  $t$  yields  $t = \sqrt{\frac{2y_0}{g}}$ . For the velocity at the time of impact:  $v = y' = -gt + v_0 = -gt = -\sqrt{2gy_0}$ .
20.  $x'' = a \quad x' = at + v_0, v_0 = x_0 = 0 \Rightarrow x = \frac{at^2}{2} + 0$ .  
 $88 = a(8) \Rightarrow a = 11 \text{ ft/sec}^2$ . At  $t = 8$ ,  $x = 11 \left( \frac{64}{2} \right) = 352 \text{ ft}$ .

21.  $a = y'' = 32 - \varepsilon \sin\left(\frac{\pi t}{4}\right)$ . Integrating gives us  $y' = -32t - \frac{4}{\pi} \varepsilon \cos\left(\frac{\pi t}{4}\right) + C$ . The object is dropped from rest, so  $y'(0) = 0 = -\frac{4}{\pi} \varepsilon + C$ . Solving for  $C$  yields  $C = \frac{4}{\pi} \varepsilon$ , and putting this value back into the equation for  $y'$  and simplifying gives us  $y' = -32t + \frac{4}{\pi} \varepsilon \left(1 - \cos\left(\frac{\pi t}{4}\right)\right)$ . Integrating again gives us  $y = -16t^2 + \frac{4}{\pi} \varepsilon t - \left(\frac{4}{\pi}\right)^2 \varepsilon \sin\left(\frac{\pi t}{4}\right) + C'$ . Since the object is dropped from a height of 252 ft. (at  $t = 0$ ),  $y(0) = C' = 252$  and thus
- $$y = -16t^2 + \frac{4}{\pi} \varepsilon t - \left(\frac{4}{\pi}\right)^2 \varepsilon \sin\left(\frac{\pi t}{4}\right) + 252.$$
- Finally, since  $y(4) = 0$ ,
- $$y(4) = 0 = -16 \cdot 4^2 + \frac{4\varepsilon}{\pi} \cdot 4 - \left(\frac{4}{\pi}\right)^2 \varepsilon \sin(\pi) + 252.$$
- Solving for  $\varepsilon$  yields  $\varepsilon = \frac{\pi}{4}$ .

## Section 1.2

- 1 (a). The equation is autonomous because  $y'$  depends only on  $y$ .
- 1 (b). Setting  $y' = 0$ , we have  $0 = -y + 1$ . Solving this for  $y$  yields the equilibrium solution:  $y = 1$ .
- 2 (a). not autonomous
- 2 (b). no equilibrium solutions, isoclines are  $t = \text{constant}$ .
- 3 (a). The equation is autonomous because  $y'$  depends only on  $y$ .
- 3 (b). Setting  $y' = 0$ , we have  $0 = \sin y$ . Solving this for  $y$  yields the equilibrium solutions:  $y = \pm n\pi$ .
- 4 (a). autonomous
- 4 (b).  $y(y - 1) = 0$ ,  $y = 0, 1$ .
- 5 (a). The equation is autonomous because  $y'$  does not depend explicitly on  $t$ .
- 5 (b). There are no equilibrium solutions because there are no points at which  $y' = 0$ .
- 6 (a). not autonomous
- 6 (b).  $y = 0$  is equilibrium solution, isoclines are hyperbolas.
- 7 (a).  $c = -1$ : Setting  $c = -1$  gives us  $-y + 1 = -1$  which, solved for  $y$ , reads  $y = 2$ . This is the isocline for  $c = -1$ .
- $c = 0$ : Setting  $c = 0$  gives us  $-y + 1 = 0$  which, solved for  $y$ , reads  $y = 1$ . This is the isocline for  $c = 0$ .
- $c = 1$ : Setting  $c = 1$  gives us  $-y + 1 = 1$  which, solved for  $y$ , reads  $y = 0$ , the isocline for  $c = 1$ .

8 (a).  $-y + t = -1 \Rightarrow y = t + 1$

$-y + t = 0 \Rightarrow y = t$

$-y + t = 1 \Rightarrow y = t - 1$

9 (a).  $c = -1$ : Setting  $c = -1$  gives us  $y^2 - t^2 = -1$  which can be simplified to  $t^2 - y^2 = 1$  (a hyperbola). This is the isocline for  $c = -1$ .

$c = 0$ : Setting  $c = 0$  gives us  $y^2 - t^2 = 0$  which can be simplified to  $y = \pm t$ . This is the isocline for  $c = 0$ .

$c = 1$ : Setting  $c = 1$  gives us  $y^2 - t^2 = 1$  (a hyperbola). This is the isocline for  $c = 1$ .

10.  $f(0) = f(2) = 0 \quad y' = y(2 - y)$

$y' > 0$  for  $0 < y < 2$ ,  $y' < 0$  for  $-\infty < y < 0$  and  $2 < y < \infty$ .

11. One example that would fit these criteria is  $y' = -(y - 1)^2$ . For this autonomous D.E.,  $y' = 0$  at  $y = 1$  and  $y' < 0$  for  $-\infty < y < 1$  and  $1 < y < \infty$ .

12.  $y' = 1$ .

13. One example that would fit these criteria is  $y' = \sin(2\pi y)$ . For this autonomous D.E.,  $y' = 0$  at

$$y = \frac{n}{2}.$$

14. c.

15. f.

16. a.

17. b.

18. d.

19. e.