

5.1-1

$$\Pi_P = \int_0^{L_T} \left(\frac{1}{2} AE \tilde{u}_{,x}^2 - c x \tilde{u} \right) dx - P u_L$$

Assume $\tilde{u} = a_1 x + a_2 x^2$, then $\tilde{u}_{,x} = a_1 + 2a_2 x$

$$\tilde{u}_{,x}^2 = a_1^2 + 4a_1 a_2 x + 4a_2^2 x^2$$

$$\Pi_P = \frac{AE}{2} \left(a_1^2 L_T + 2a_1 a_2 L_T^2 + \frac{4}{3} a_2^2 L_T^3 \right) - c \left(a_1 \frac{L_T^3}{3} + a_2 \frac{L_T^4}{4} \right) - P(a_1 L_T + a_2 L_T^2)$$

$$\frac{\partial \Pi_P}{\partial a_1} = 0 = AE(a_1 L_T + a_2 L_T^2) - \frac{c L_T^3}{3} - P L_T$$

$$\frac{\partial \Pi_P}{\partial a_2} = 0 = AE \left(a_1 L_T + \frac{4}{3} a_2 L_T^3 \right) - \frac{c L_T^4}{4} - P L_T^2$$

$$\begin{bmatrix} 1 & L_T \\ L_T & \frac{4}{3} L_T^2 \end{bmatrix} \begin{Bmatrix} a_1 \\ a_2 \end{Bmatrix} = \begin{Bmatrix} \frac{c L_T^2}{3AE} + \frac{P}{AE} \\ \frac{c L_T^3}{4AE} + \frac{P L_T}{AE} \end{Bmatrix}$$

$$\begin{Bmatrix} a_1 \\ a_2 \end{Bmatrix} = \frac{3}{L_T^2} \begin{bmatrix} \frac{4}{3} L_T^2 & -L_T \\ -L_T & 1 \end{bmatrix} \begin{Bmatrix} \frac{c L_T^2}{3AE} + \frac{P}{AE} \\ \frac{c L_T^3}{4AE} + \frac{P L_T}{AE} \end{Bmatrix} = \begin{Bmatrix} \frac{7c L_T^2}{12AE} + \frac{P}{AE} \\ -\frac{c L_T}{4AE} \end{Bmatrix}$$

$$\tilde{u} = \frac{P}{AE} x + \frac{7c L_T^2}{12AE} x - \frac{c L_T}{4AE} x^2$$

same as Eq. 5.1-10

5.1-2

$$\int_0^L W [EI \tilde{v}_{xxxx} - q] dx = 0, \quad \tilde{v} = ax(L-x)$$

Integrate by parts twice: W

$$\int_0^L W_{,x} [-EI \tilde{v}_{xxx}] dx - \int_0^L W q dx + EI [W \tilde{v}_{xxx}]_0^L = 0$$

But $W = 0$ at $x=0$ and at $x=L$; $[\downarrow] = 0$

$$\int_0^L W_{,xx} [EI \tilde{v}_{xx}] dx - \int_0^L W q dx - EI [W_{,x} \tilde{v}_{xx}]_0^L = 0$$

But, as nonessential boundary condition, ends are simply supported; $\tilde{v}_{xx} = 0$ at ends.

Also $\tilde{v}_{,xx} = -2a$ and $W_{,xx} = -2$, so

$$\int_0^L -2EI(-2a) dx - \int_0^L x(L-x)q dx = 0 \text{ and}$$

$$a = \frac{1}{4EIL} \int_0^L x(L-x)q dx; \text{ center } \tilde{v} = a \frac{L^2}{4}$$

(a) $q = q_0 \sin \frac{\pi x}{L}$. Let $\theta = \frac{\pi x}{L}$; then

$$a = \frac{1}{4EIL} \int_0^L x(L-x) q_0 \sin \frac{\pi x}{L} dx \text{ becomes}$$

$$a = \frac{L^2 q_0}{EI \pi^2} \int_0^\pi \theta (1 - \frac{\theta}{\pi}) \sin \theta d\theta = 0.03225 \frac{q_0 L^2}{EI}$$

$$\text{At center, } \tilde{v} = a \frac{L^2}{4} = 0.00806 \frac{q_0 L^4}{EI}$$

Exact $v = v_c \sin \frac{\pi x}{L}$ where $v_c =$ center v .

$$EI v_{xxxx} = q, \quad EI \frac{\pi^4}{L^4} v_c \sin \frac{\pi x}{L} = q_0 \sin \frac{\pi x}{L}$$

$$\frac{a \cdot L^4}{\pi^4 EI} = \frac{0.01027 q_0 L^4}{EI}$$

Approx. center deflection is 21.5% low.

$M = EI v_{,xx}$: at center,

$$\text{exact } M_c = EI \frac{q_0 L^4}{\pi^4 EI} \left(-\frac{\pi^2}{L^2} \right)$$

$$= 0.1013 q_0 L^2$$

$$\text{Approx. } M = EI(-2a) = 0.0645 q_0 L^2 \quad (36\% \text{ low})$$

$$a = \frac{q_0}{4EIL} \int_0^L x(L-x) dx = \frac{q_0}{4EIL} \frac{L^2}{4} \frac{2L}{3} = \frac{q_0 L^2}{24EI}$$

$$\text{At center, } \tilde{v} = a \frac{L^2}{4} = \frac{q_0 L^4}{96EI} = 0.01042 \frac{q_0 L^4}{EI}$$

$$\text{Exact is } \frac{5q_0 L^4}{384EI} = 0.01302 \frac{q_0 L^4}{EI}$$

Approx. center deflection is 20.0% low.

$$\text{At center, exact } M_c = \frac{q_0 L^2}{8}$$

$$\text{Approx. } M = EI(-2a) = \frac{q_0 L^2}{12}$$

(33% low)

5.2-1

At $x = \frac{L_T}{3}$, from collocation:

$$\tilde{u} = \left(\frac{P}{AE} + \frac{cL_T^2}{2AE} \right) \frac{L_T}{3} - \frac{cL_T}{6AE} \frac{L_T^2}{9} = \frac{PL_T}{3AE} - \frac{4cL_T^3}{27AE}$$

At $x = \frac{L_T}{3}$, exact solution (Eq. 5.1-4):

$$u = \frac{PL_T}{3AE} + \frac{cL_T^2}{2AE} \frac{L_T}{3} - \frac{c}{6AE} \frac{L_T^3}{27} = \frac{PL_T}{3AE} - \frac{4.33cL_T^3}{27AE}$$

That $\tilde{u} \neq u$ at the collocation point does not imply an error. The residual depends on derivatives of \tilde{u} . Making the residual vanish at a certain point does not imply that the dependent variable is exact at that point.

5.2-2

$$\frac{d^2 u}{dx^2} + \frac{c}{AE} = 0 \quad \text{in } V$$

$$\frac{du}{dx} = \frac{P}{AE} \quad \text{at } x = L_T$$

Assume $\tilde{u} = a_1 x + a_2 x^2$

then $R = 2a_2 + \frac{c}{AE}$

$$R_B = a_1 + 2a_2 L_T - \frac{P}{AE}$$

Collocation Point doesn't matter; $a_2 = -\frac{c}{2AE}$ from $R=0$

$$a_1 - \frac{cL_T}{AE} - \frac{P}{AE} = 0; \quad a_1 = \frac{P}{AE} + \frac{cL_T}{AE} \quad \text{from } R_B = 0$$

$$u = \frac{Px}{AE} + \frac{c}{AE} \left(L_T x - \frac{x^2}{2} \right) \quad [\text{exact}]$$

Subdomain $\int_0^{L_T} \left(2a_2 + \frac{c}{AE} \right) dx = 0; \quad a_2 = -\frac{c}{2AE}$ Same results as above.

Least Squares ($\alpha = \frac{1}{L_T}$)

$$I = \int_0^{L_T} \left(2a_2 + \frac{c}{AE} \right)^2 dx + \frac{1}{L_T} \left[a_1 + 2a_2 L_T - \frac{P}{AE} \right]^2$$

$$I = \left(2a_2 + \frac{c}{AE} \right)^2 L_T + \frac{1}{L_T} \left[a_1 + 2a_2 L_T - \frac{P}{AE} \right]^2$$

$$\frac{\partial I}{\partial a_1} = \frac{2}{L_T} \left(a_1 + 2a_2 L_T - \frac{P}{AE} \right) = 0, \quad \frac{\partial I}{\partial a_2} = 2L_T \left(2a_2 + \frac{c}{AE} \right) + \frac{2}{L_T} [\dots] 2L_T = 0$$

$$\frac{2}{L_T} a_1 + 4a_2 = \frac{2P}{AEL_T}$$

Same results as above.

$$4a_1 + 16L_T a_2 = \frac{4P}{AE} - \frac{4cL_T}{AE}$$

Least Squares Collocation (at $x = \frac{L_T}{3}$ and $x = L_T$ for R , at $x = L$ for R_B . Also set $\alpha = 1/L_T$.)

$$\begin{Bmatrix} R_1 \\ R_2 \\ R_3 \end{Bmatrix} = \begin{bmatrix} 0 & 2 \\ 0 & 2 \\ 1/L_T & 2 \end{bmatrix} \begin{Bmatrix} a_1 \\ a_2 \end{Bmatrix} - \begin{Bmatrix} -c/AE \\ -c/AE \\ P/AEL_T \end{Bmatrix}$$

$$\begin{bmatrix} 0 & 0 & 1/L_T \\ 2 & 2 & 2 \end{bmatrix} \begin{bmatrix} 0 & 2 \\ 0 & 2 \\ 1/L_T & 2 \end{bmatrix} \begin{Bmatrix} a_1 \\ a_2 \end{Bmatrix} = \begin{bmatrix} 0 & 0 & 1/L_T \\ 2 & 2 & 2 \end{bmatrix} \begin{Bmatrix} -c/AE \\ -c/AE \\ P/AEL_T \end{Bmatrix}$$

$$\begin{bmatrix} 1/L_T^2 & 2/L_T \\ 2/L_T & 12 \end{bmatrix} \begin{Bmatrix} a_1 \\ a_2 \end{Bmatrix} = \begin{Bmatrix} P/AEL_T^2 \\ -4c/AE + 2P/AEL_T \end{Bmatrix} \quad \text{Same results as above}$$

[continued, next page]

5.2-2 (continued) Galerkin

$$R_i = \int_0^{L_T} \left(-\frac{dW_i}{dx} \frac{d\tilde{u}}{dx} + W_i \frac{c}{AE} \right) dx + W_i \frac{P}{AE} \Big|_{L_T} \quad \text{where } \begin{matrix} W_1 = x \\ W_2 = x^2 \end{matrix}$$

$$0 = \int_0^{L_T} \left[(-1)(a_1 + 2a_2x) + x \frac{c}{AE} \right] dx + \frac{PL_T}{AE}$$

$$0 = \int_0^{L_T} \left[(-2x)(a_1 + 2a_2x) + x^2 \frac{c}{AE} \right] dx + \frac{PL_T^2}{AE}$$

$$0 = -L_T a_1 - L_T^2 a_2 + \frac{cL_T^2}{2AE} + \frac{PL_T}{AE}$$

$$0 = -L_T^2 a_1 - \frac{4}{3} L_T^3 a_2 + \frac{cL_T^3}{3} + \frac{PL_T^2}{AE}$$

$$\begin{bmatrix} 1 & L_T \\ L_T & 4L_T^2/3 \end{bmatrix} \begin{Bmatrix} a_1 \\ a_2 \end{Bmatrix} = \begin{Bmatrix} cL_T/2AE + P/AE \\ cL_T^2/3AE + PL_T/AE \end{Bmatrix} \quad \text{Same results as before}$$

5.2-3

Exact values: At $x=0.5$, $u = 1.1492$

At $x=0.7$, $u = 0.8325$

Residual methods:

$$\tilde{u} = 3 - 2x + a(x^2 - x), \quad \tilde{u}_{,x} = -2 + a(2x - 1),$$

$$\tilde{u}_{,xx} = 2a, \quad R = 4ax^2 - (4a + 8)x + 2a$$

(a) $R=0$ at $x = \frac{1}{2}$ yields $a = 4$
and $\tilde{u} = 4x^2 - 6x + 3$

At $x=0.5$, $\tilde{u} = 1.00$; -13.0% error

At $x=0.7$, $\tilde{u} = 0.76$; -8.7% error

(b) $\int_0^1 R dx = \frac{4a}{3} - (2a + 4) + 2a = 0$ yields
 $a = 3$ and $\tilde{u} = 3x^2 - 5x + 3$

At $x=0.5$, $\tilde{u} = 1.25$; $+8.8\%$ error

At $x=0.7$, $\tilde{u} = 0.97$; $+16.5\%$ error

(c) $\frac{\partial}{\partial a} \int_0^1 R^2 dx = 0, \quad \int_0^1 R \frac{\partial R}{\partial a} dx = 0$

$$\int_0^1 [4ax^2 - (4a + 8)x + 2a](4x^2 - 4x + 2) dx = 0$$

yields $a = \frac{20}{7}, \quad \tilde{u} = \frac{20}{7}x^2 - \frac{34}{7}x + 3$

At $x=0.5$, $\tilde{u} = 1.2857$; $+11.9\%$ error

At $x=0.7$, $\tilde{u} = 1.0000$; $+20.1\%$ error

(d) $I = \left[\frac{4a}{9} - \frac{4a}{3} - \frac{8}{3} + 2a \right]^2 + \left[\frac{16a}{9} - \frac{8a}{3} - \frac{16}{3} + 2a \right]^2$
 $I = \frac{200a^2}{81} - \frac{160a}{9} + \frac{320}{9}, \quad \frac{\partial I}{\partial a} = \frac{400a}{81} - \frac{160}{9}$

$\frac{\partial I}{\partial a} = 0$ yields $a = \frac{18}{5}, \quad \tilde{u} = \frac{18}{5}x^2 - \frac{28}{5}x + 3$

At $x=0.5$, $\tilde{u} = 1.100$; -4.3% error

At $x=0.7$, $\tilde{u} = 0.844$; $+1.4\%$ error

(e) $\frac{\partial \tilde{u}}{\partial a} = x^2 - x, \quad \int_0^1 (x^2 - x)R dx = 0$

yields $a = \frac{10}{3}, \quad \tilde{u} = \frac{10}{3}x^2 - \frac{16}{3}x + 3$

At $x=0.5$, $\tilde{u} = 1.1667$; $+1.5\%$ error

At $x=0.7$, $\tilde{u} = 0.9000$; $+8.1\%$ error

5.2-4

Exact values: At $x=0.5$, $u=1.4715$

Residual methods: At $x=0.7$, $u=2.5864$

$$\tilde{u} = a_1 x + a_2 x^2, \quad \tilde{u}_{,x} = a_1 + 2a_2 x$$

$$R = \tilde{u}_{,x} + 2\tilde{u} - 16x = (1+2x)a_1 + 2x(1+x)a_2 - 16x$$

$$(a) \begin{Bmatrix} R_1 \\ R_2 \\ R_3 \end{Bmatrix} = \begin{bmatrix} 1.5 & 0.625 \\ 2.0 & 1.500 \\ 2.5 & 2.625 \end{bmatrix} \begin{Bmatrix} a_1 \\ a_2 \end{Bmatrix} - \begin{Bmatrix} 4 \\ 8 \\ 12 \end{Bmatrix} = [Q]\{a\} - \{c\}$$

$$\text{Apply Eq. 5.2-13c: } \begin{bmatrix} 12.5 & 10.5 \\ 10.5 & 9.5313 \end{bmatrix} \begin{Bmatrix} a_1 \\ a_2 \end{Bmatrix} = \begin{Bmatrix} 52 \\ 46 \end{Bmatrix}$$

$$\begin{Bmatrix} a_1 \\ a_2 \end{Bmatrix} = \begin{Bmatrix} 1.4202 \\ 3.2616 \end{Bmatrix}, \quad \tilde{u} = 1.4202x + 3.2616x^2$$

$$\text{At } x=0.5, \tilde{u} = 1.5255; \quad +3.7\% \text{ error}$$

$$\text{At } x=0.7, \tilde{u} = 2.5923; \quad +0.2\% \text{ error}$$

$$(b) \frac{\partial \tilde{u}}{\partial a_1} = x, \quad \frac{\partial \tilde{u}}{\partial a_2} = x^2; \quad \text{set } \int_0^1 x R dx = \int_0^1 x^2 R dx = 0$$

Thus

$$\left. \begin{aligned} \left(\frac{1}{2} + \frac{2}{3}\right)a_1 + \left(\frac{2}{3} + \frac{1}{2}\right)a_2 - \frac{16}{3} &= 0 \\ \left(\frac{1}{3} + \frac{1}{2}\right)a_1 + \left(\frac{1}{2} + \frac{2}{5}\right)a_2 - 4 &= 0 \end{aligned} \right\} \begin{aligned} a_1 &= 1.7143 \\ a_2 &= 2.8571 \end{aligned}$$

$$\text{At } x=0.5, \tilde{u} = 1.5714; \quad +6.8\% \text{ error}$$

$$\text{At } x=0.7, \tilde{u} = 2.5429; \quad -1.7\% \text{ error}$$

5.2-5 $\tilde{u} = a_1 x + a_2 x^2$ $R = 2a_2 + cx$

$R_S = (a_1 + 2a_2 L_T) - b$

(a) $R = 0 = 2a_2 + c \frac{L_T}{2}$,

$R_S = 0$ yields $a_1 = b + \frac{cL_T}{2}$

For $b=0$ & $c=L_T=1$, $\tilde{u} = \frac{x}{2} - \frac{x^2}{4}$, $\tilde{u}_{,x} = \frac{1}{2} - \frac{x}{2}$

(b) $\int_0^{L_T/2} (2a_2 + cx) dx = 2a_2 \frac{L_T}{2} + \frac{c}{2} \left(\frac{L_T}{2}\right)^2 = 0$, $a_2 = -\frac{cL_T}{8}$

$R_B = 0$ yields $a_1 = b + \frac{cL_T}{4}$

For $b=0$ & $c=L_T=1$, $\tilde{u} = \frac{x}{4} - \frac{x^2}{8}$, $\tilde{u}_{,x} = \frac{1}{4} - \frac{x}{4}$

(c)
$$\begin{Bmatrix} R_1 \\ R_2 \\ R_3 \\ R_S \end{Bmatrix} = \begin{bmatrix} 0 & 2 \\ 0 & 2 \\ 0 & 2 \\ 1/L_T & 2 \end{bmatrix} \begin{Bmatrix} a_1 \\ a_2 \end{Bmatrix} - \begin{Bmatrix} 0 \\ -cL_T/2 \\ -cL_T \\ b/L_T \end{Bmatrix}$$

$$\begin{bmatrix} \frac{1}{L_T} & \frac{2}{L_T} \\ \frac{2}{L_T} & 1/b \end{bmatrix} \begin{Bmatrix} a_1 \\ a_2 \end{Bmatrix} = \begin{Bmatrix} \frac{b}{L_T} \\ -\frac{3c}{L_T} + \frac{2b}{L_T} \end{Bmatrix}, \begin{Bmatrix} a_1 \\ a_2 \end{Bmatrix} = \begin{Bmatrix} b + \frac{cL_T}{2} \\ -\frac{cL_T}{4} \end{Bmatrix}$$

For $b=0$ & $c=L_T=1$, $\tilde{u} = \frac{x}{2} - \frac{x^2}{4}$, $\tilde{u}_{,x} = \frac{1}{2} - \frac{x}{2}$

(d) Becomes simple collocation

$$\begin{bmatrix} 0 & 2 \\ 1/L_T & 2 \end{bmatrix} \begin{Bmatrix} a_1 \\ a_2 \end{Bmatrix} - \begin{Bmatrix} -cL_T/3 \\ b/L_T \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \end{Bmatrix}, \begin{Bmatrix} a_1 \\ a_2 \end{Bmatrix} = \begin{Bmatrix} b + \frac{cL_T}{3} \\ -\frac{cL_T}{6} \end{Bmatrix}$$

For $b=0$ & $c=L_T=1$, $\tilde{u} = \frac{x}{3} - \frac{x^2}{6}$, $\tilde{u}_{,x} = \frac{1}{3} - \frac{x}{3}$

Summary of foregoing results:

	(a)	(b)	(c)	(d)	(exact)
$u @ L_T/2$.1875	.0938	.1875	.1250	.2292
$u @ L_T$.2500	.1250	.2500	.1667	.3333
$u @ \wedge$.5000	.2500	.5000	.3333	.5000
$u_{,x} @ L_T/2$.2500	.1250	.2500	.1667	.3750
$u_{,x} @ L_T$	0	0	0	0	0

(e) Consider n residuals R_i . Let $c_i = \text{constants}$. Form of Eq. 15.3-7, becomes

$$\begin{Bmatrix} R_1 \\ R_2 \\ \vdots \\ R_S \end{Bmatrix} = \begin{bmatrix} 0 & 2 \\ 0 & 2 \\ \vdots & \vdots \\ \alpha & 2\alpha \end{bmatrix} \begin{Bmatrix} a_1 \\ a_2 \end{Bmatrix} - \begin{Bmatrix} c_1 \\ c_2 \\ \vdots \\ \alpha b \end{Bmatrix}$$

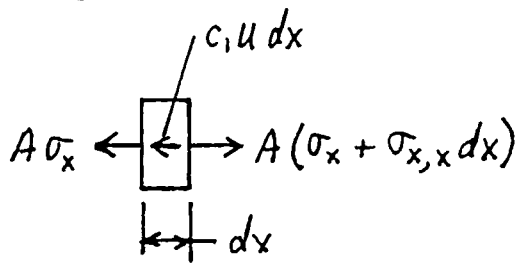
Form of Eq. 15.3-8c, & its solution, are

$$\begin{bmatrix} \alpha^2 & 2\alpha^2 \\ 2\alpha^2 & 4n+4\alpha^2 \end{bmatrix} \begin{Bmatrix} a_1 \\ a_2 \end{Bmatrix} = \begin{Bmatrix} \alpha^2 b \\ 2\sum c_i + 2\alpha^2 b \end{Bmatrix}$$

$$\begin{Bmatrix} a_1 \\ a_2 \end{Bmatrix} = \frac{1}{4n\alpha^2} \begin{bmatrix} 4n+4\alpha^2 & -2\alpha^2 \\ -2\alpha^2 & \alpha^2 \end{bmatrix} \begin{Bmatrix} \alpha^2 b \\ 2\sum c_i + 2\alpha^2 b \end{Bmatrix} = \begin{Bmatrix} b - \frac{1}{n} \sum c_i \\ \frac{1}{2n} \sum c_i \end{Bmatrix}$$

This result is independent of α due to the fortuitous absence of α from interior residuals.

5.3-1



Axial equilibrium:

$$\left. \begin{aligned} A\sigma_{x,x} - c_1 u &= 0 \\ \sigma_x &= E u_{,x} \end{aligned} \right\} AE u_{,xx} - c_1 u = 0$$

Assume $\tilde{u} = \underline{[N]} \{d\} = \left[\frac{L-x}{L} \quad \frac{x}{L} \right] \begin{Bmatrix} u_1 \\ u_2 \end{Bmatrix}$ over one element of length L

$$R=0 = \int_0^L \underline{[N]}^T (AE \tilde{u}_{,xx} - c_1 \tilde{u}) dx$$

Substitute for \tilde{u} and integrate by parts

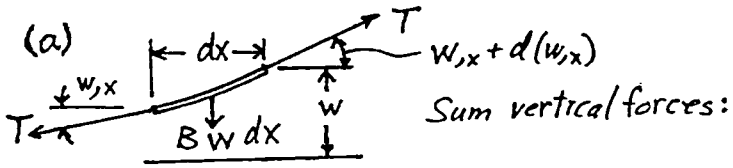
$$0 = \int_0^L \underline{[N_{,x}]}^T \underline{[N_{,x}]} AE dx \{d\} + \int_0^L \underline{[N]}^T \underline{[N]} c_1 dx \{d\} - \left[\underline{[N]}^T AE \tilde{u}_{,x} \right]_0^L$$

$$\left(\frac{AE}{L} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} + c_1 L \begin{bmatrix} 1/3 & 1/6 \\ 1/6 & 1/3 \end{bmatrix} \right) \begin{Bmatrix} u_1 \\ u_2 \end{Bmatrix} = \begin{Bmatrix} (-AE \tilde{u}_{,x})_0 \\ (AE \tilde{u}_{,x})_L \end{Bmatrix}$$

$$\left(\frac{AE}{L} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} + \frac{c_1 L}{6} \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix} \right) \begin{Bmatrix} u_1 \\ u_2 \end{Bmatrix} = \begin{Bmatrix} P \\ -F \end{Bmatrix}$$

where $F = c_2 u_L$

5.3-2



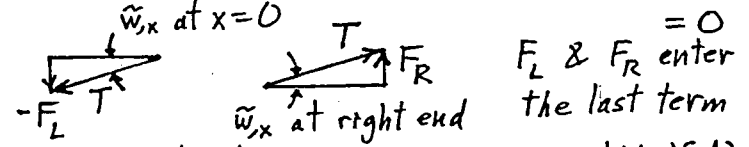
$$-T w_{,x} + T [w_{,x} + d(w_{,x})] - B w dx = 0$$

$$T d(w_{,x}) = B w dx, \quad T w_{,xx} - B w = 0$$

(b) $\tilde{w} = [N] \{d\}$ and $\int_0^L [N]^T (T \tilde{w}_{,xx} - B \tilde{w}) dx = 0$

Integrate by parts

$$\int_0^L (-[N_{,x}]^T T \tilde{w}_{,x} - [N]^T B \tilde{w}) dx + \sum [[N]^T T \tilde{w}_{,x}]_0^L$$



Also substitute $\tilde{w} = [N] \{d\}$ & $\tilde{w}_{,x} = [N_{,x}] \{d\}$

$$\sum \left(\underbrace{\int_0^L [N_{,x}]^T T [N_{,x}] dx}_{[k]} + \underbrace{\int_0^L [N]^T B [N] dx}_{[k_f]} \right) \{d\} = \begin{Bmatrix} F_L \\ \vdots \\ F_R \end{Bmatrix}$$

5.3-3

$$(a) \int_0^L [N] \left(T \tilde{w}_{,xx} - \rho_L \ddot{w} \right) dx = 0$$

Also, $\tilde{w} = [N] \{d\}$. Integrate by parts.

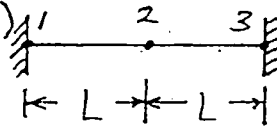
$$-\int_0^L [N_{,x}]^T T \tilde{w}_{,x} dx - \int_0^L [N]^T \rho_L \ddot{w} dx + \left[[N]^T T \tilde{w}_{,x} \right]_0^L = 0$$

Last term associated with transverse support forces, whose d.o.f. are discarded for simply supported ends. Subs: $\tilde{w} = [N] \{d\}$, $\tilde{w}_{,x} = [N_{,x}] \{d\}$

$$\underbrace{\int_0^L [N_{,x}]^T [N_{,x}] dx}_{[k]} \{d\} + \underbrace{\int_0^L [N]^T \rho_L [N] dx}_{[m]} \{d\} = 0$$

Here $[N] = \left[\frac{L-x}{L} \quad \frac{x}{L} \right]$ and $[N_{,x}] = \frac{1}{L} \begin{bmatrix} -1 & 1 \end{bmatrix}$

$$[k] = \frac{T}{L} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}, \quad [m] = \frac{\rho_L L}{6} \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}$$

(b)  Assemble two elements & suppress d.o.f. w_1 & w_3 .

Thus
$$2 \frac{T}{L} w_2 + 4 \frac{\rho_L L}{6} \ddot{w}_2 = 0$$

Set $w_2 = \bar{w}_2 \sin \omega t$

$$\ddot{w}_2 = -\omega^2 \bar{w}_2 \sin \omega t \quad \left(2 \frac{T}{L} + 4 \frac{\rho_L L}{6} \omega^2 \right) \bar{w}_2 = 0$$

$$\omega^2 = 3 \frac{T}{\rho_L L^2}$$

5.3-4

Left hand side of Eq. 5.3-18, after integration by parts of the term that contains $F \tilde{v}_{,xx}$, contains the additional terms

$$+ \int_0^L [N_{,x}]^T F \tilde{v}_{,x} dx + \int_0^L [N]^T B \tilde{v} dx$$

Substitute $\tilde{v} = [N] \{d\}$ and $\tilde{v}_{,x} = [N_{,x}] \{d\}$

The additional terms become

$$+ \underbrace{\int_0^L [N_{,x}]^T F [N_{,x}] dx}_{[k_\sigma]} \{d\} + \underbrace{\int_0^L [N]^T B [N] dx}_{[k_f]} \{d\}$$

5.3-5

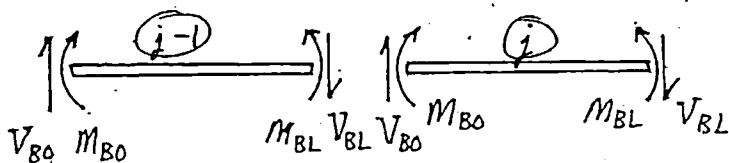
We want to show that the load terms are $\{R\} = ([N_x]^T M_B - [N]^T V_B)_0^L$

(with assembly of elements implied).

Use cubic shape functions and insert limits

0 to L:
$$\begin{Bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{Bmatrix} M_{BL} - \begin{Bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{Bmatrix} M_{B0} - \begin{Bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{Bmatrix} V_{BL} + \begin{Bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{Bmatrix} V_{B0}$$

Consider adjacent elements $j-1$ and j .



Consider e.g. assembly of vertical forces where elements $j-1$ and j meet. The dashed line connects forces having the same global d.o.f. number. These add, to yield the net force $(V_{B0})_j - (V_{BL})_{j-1}$ at the shared node.

5.3-6

$A = \frac{L-x}{L} A_1 + \frac{x}{L} A_2$. Use Eq. 5.3-23.

$[N_x]^T [N_x] = \frac{1}{L^2} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$, so integral is

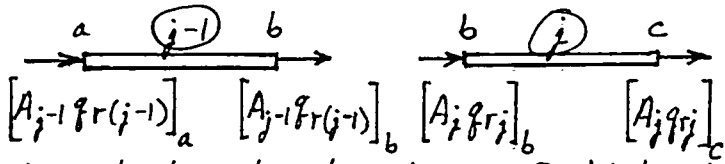
$\frac{k}{L^2} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \int_0^L \left(\frac{L-x}{L} A_1 + \frac{x}{L} A_2 \right) dx =$

$\frac{k}{L^2} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \left(\frac{A_1 L}{2} + \frac{A_2 L}{2} \right) = \frac{k(A_1 + A_2)}{2L} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$

Eq. 5.3-24 becomes: $\frac{k(A_1 + A_2)}{2L} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \begin{Bmatrix} T_1 \\ T_2 \end{Bmatrix} = \begin{Bmatrix} A_1 q_1 \\ A_2 q_2 \end{Bmatrix}$

5.3-7

Consider adjacent els. $j-1$ and j .



Connect elements at node b . Right-hand side of Eq. 5.3-23 becomes

$$\begin{matrix} \text{node } a & \text{---} & \left\{ \begin{matrix} A_{j-1} q_{r(j-1)} \\ -A_{j-1} q_{r(j-1)} \end{matrix} \right\} \\ \text{node } b & \text{---} & \left\{ \begin{matrix} A_{j-1} q_{r(j-1)} \\ -A_{j-1} q_{r(j-1)} \end{matrix} \right\} + \left\{ \begin{matrix} A_j q_{rj} \\ -A_j q_{rj} \end{matrix} \right\} \\ \text{node } c & \text{---} & \left\{ \begin{matrix} A_j q_{rj} \\ -A_j q_{rj} \end{matrix} \right\} \end{matrix} = \begin{matrix} \left\{ \begin{matrix} A_{j-1} q_{r(j-1)} \\ \Delta \\ -A_j q_{rj} \end{matrix} \right\} \end{matrix}$$

where $\Delta = [A_j q_{rj}]_b - [A_{j-1} q_{r(j-1)}]_b = 0$

because of interelement continuity. The other two entries are complete if there are no additional elements.

5.5-1

Write $\phi_{,x}^2 = \phi_{,x}^T \phi_{,x}$ and $\phi_{,y}^2 = \phi_{,y}^T \phi_{,y}$

Substitute $\phi = \underline{N} \underline{\phi}_e$, $\phi_{,x} = \underline{N}_{,x} \underline{\phi}_e$, $\phi_{,y} = \underline{N}_{,y} \underline{\phi}_e$

$$\Pi = \frac{1}{2} \underline{\phi}_e^T \iint \left(\underline{N}_{,x}^T k_x \underline{N}_{,x} + \underline{N}_{,y}^T k_y \underline{N}_{,y} \right) dx dy \underline{\phi}_e$$
$$- \underline{\phi}_e^T \iint \underline{N}^T Q dx dy - \underline{\phi}_e^T \int \underline{N}^T f_B dS$$

$$\left\{ \frac{\partial \Pi}{\partial \underline{\phi}_e} \right\} = 0 = \iint \left(\underline{N}_{,x}^T k_x \underline{N}_{,x} + \underline{N}_{,y}^T k_y \underline{N}_{,y} \right) dx dy \underline{\phi}_e$$
$$- \iint \underline{N}^T Q dx dy - \int \underline{N}^T f_B dS$$

5.5-2

Residual equation is

$$\int_{\tilde{N}} N^T \left(\tilde{P}_{,xx} + \tilde{P}_{,yy} + \tilde{P}_{,zz} + \frac{\omega^2}{c^2} \tilde{P} \right) dV = 0 \quad (A)$$

Integrate by parts (see Eq. 5.5-5, with $k_x = k_y = k_z = 1$). $\tilde{P}_{,n} = 0$

$$\int_{\tilde{N}} N^T \nabla^2 \tilde{P} dV = \int_{\tilde{N}} N^T (\tilde{p}_{,x} l + \tilde{p}_{,y} m + \tilde{p}_{,z} n) dS - \int (N_{,x}^T \tilde{P}_{,x} + N_{,y}^T \tilde{P}_{,y} + N_{,z}^T \tilde{P}_{,z}) dV$$

Hence, with $\tilde{p}_{,x} = N_{,x}^T p_e$ etc., Eq. (A) becomes

$$\int (N_{,x}^T N_{,x} + N_{,y}^T N_{,y} + N_{,z}^T N_{,z}) dV p_e - \omega^2 \int \frac{1}{c^2} N^T N dV p_e = 0$$

5.5-3

Apply integ. by parts. First, use
Eq. 5.4-7 on first term of -

$$\int_{\tilde{V}} N^T \left(\frac{1}{r} (r \tilde{\phi}_{,r})_{,r} + \frac{1}{r^2} \tilde{\phi}_{,\theta\theta} + \tilde{\phi}_{,zz} + \frac{Q}{k} \right) dV = 0$$

Thus

$$\int_{\tilde{V}} N^T \left(\frac{1}{r} (r \tilde{\phi}_{,r})_{,r} \right) dV = - \int_{\tilde{V}} N_{,r}^T \tilde{\phi}_{,r} dV + \int_{\tilde{S}} N^T \tilde{\phi}_{,r} l dS$$

Integration of second term by parts produces no surface integral because $m=0$ for a normal to the boundary.

$$\int_{\tilde{V}} N^T \frac{1}{r^2} \tilde{\phi}_{,\theta\theta} dV = - \int_{\tilde{V}} N_{,\theta}^T \frac{1}{r^2} \tilde{\phi}_{,\theta} dV. \text{ Finally}$$

$$\int_{\tilde{V}} N^T \tilde{\phi}_{,zz} dV = - \int_{\tilde{V}} N_{,z}^T \tilde{\phi}_{,z} dV + \int_{\tilde{S}} N^T \tilde{\phi}_{,z} n dS$$

With the given boundary condition, we have

$$\int_{\tilde{V}} \left(N_{,r}^T \tilde{\phi}_{,r} + N_{,\theta}^T \frac{1}{r^2} \tilde{\phi}_{,\theta} + N_{,z}^T \tilde{\phi}_{,z} \right) k dV + \int_{\tilde{S}} N^T Q dV + \int_{\tilde{S}} N^T F_B dS$$

Substitute $\tilde{\phi}_{,r} = N_{,r} \phi$, etc. Thus

$$\int_{\tilde{V}} \left(N_{,r}^T N_{,r} + \frac{1}{r^2} N_{,\theta}^T N_{,\theta} + N_{,z}^T N_{,z} \right) k dV \phi = \mathcal{Q}$$

$$\text{where } \mathcal{Q} = \int_{\tilde{V}} N^T Q dV + \int_{\tilde{S}} N^T F_B dS$$

Note: $dV = r dr dz$ for a 1-radian segment.

5.5-4

Multiply by weighting function N^T .

$$\iint N^T (\tilde{\Psi}_{,xx} + \tilde{\Psi}_{,yy} + A\tilde{\Psi}_{,x} + B\tilde{\Psi}_{,y} + C) dx dy = 0 \quad (A)$$

Integrate first two terms by parts.

$$\iint N^T \tilde{\Psi}_{,xx} dx dy = - \iint N_{,x}^T \tilde{\Psi}_{,x} dx dy + \int N^T \tilde{\Psi}_{,x} l dS$$

$$\iint N^T \tilde{\Psi}_{,yy} dx dy = - \iint N_{,y}^T \tilde{\Psi}_{,y} dx dy + \int N^T \tilde{\Psi}_{,y} m dS$$

Boundary terms: $\tilde{\Psi}_{,x} l + \tilde{\Psi}_{,y} m = \tilde{\Psi}_{,n} = 0$.

Subs. $\tilde{\Psi}_{,x} = N_{,x}^T \psi_e$ etc. into what remains of Eq. (A).

$$\iint \left(-N_{,x}^T N_{,x} - N_{,y}^T N_{,y} + A N^T N_{,x} + B N^T N_{,y} \right) dx dy \psi_e = - \iint N^T C dx dy$$

Here the coefficient matrix of nodal d.o.f. ψ_e is not symmetric.

5.5-5

Companions to Eq. 5.5-11 are

$$\iint \tilde{N}^T \tilde{\sigma}_{xy,y} dx dy = - \iint \tilde{N}_{,y}^T \tilde{\tau}_{xy} dx dy + \int \tilde{N}_{xy}^T m dS$$

$$\iint \tilde{N}^T \tilde{\sigma}_{xy,x} dx dy = - \iint \tilde{N}_{,x}^T \tilde{\tau}_{xy} dx dy + \int \tilde{N}_{xy}^T l dS$$

$$\iint \tilde{N}^T \tilde{\sigma}_{y,y} dx dy = - \iint \tilde{N}_{,y}^T \tilde{\sigma}_y dx dy + \int \tilde{N}_y^T m dS$$

In view of surface-traction Eqs. 5.5-8, Eqs. 5.5-10 now read

$$- \iint \begin{bmatrix} \tilde{N}_{,x}^T & \underline{0}^T & \tilde{N}_{,y}^T \\ \underline{0}^T & \tilde{N}_{,y}^T & \tilde{N}_{,x}^T \end{bmatrix} \begin{Bmatrix} \tilde{\sigma}_x \\ \tilde{\sigma}_y \\ \tilde{\tau}_{xy} \end{Bmatrix} dx dy + \iint \begin{bmatrix} \tilde{N}^T & \underline{0}^T \\ \underline{0}^T & \tilde{N}^T \end{bmatrix} \begin{Bmatrix} F_x \\ F_y \end{Bmatrix} dx dy + \int \begin{bmatrix} \tilde{N}^T & \underline{0}^T \\ \underline{0}^T & \tilde{N}^T \end{bmatrix} \begin{Bmatrix} \Phi_x \\ \Phi_y \end{Bmatrix} dS = 0$$

Or, using conventional notation,

$$- \iint [\tilde{B}]^T \{\tilde{\sigma}\} dx dy + \iint [N]^T \{F\} dx dy + \int [N]^T \{\Phi\} dS \quad (A)$$

$$\text{But } \{\tilde{\sigma}\} = [E] (\{\tilde{\epsilon}\} - \{\epsilon_0\}) + \{\sigma_0\}$$

$$\text{and } \{\tilde{\epsilon}\} = [B] \{d\}$$

$$\text{so } \{\tilde{\sigma}\} = [E][B] \{d\} - [E] \{\epsilon_0\} + \{\sigma_0\} \quad (B)$$

Eqs. (A) and (B) yield the standard eqs.

5.5-6

Consider unit thickness, as usual.

There are only radial displacements, so we need only $\tilde{u} = \tilde{N} \underline{d}$. $dV = 2\pi r dr$.

$$\int \tilde{N}^T \left(\frac{1}{r} \frac{d}{dr} (r \tilde{\sigma}_r) - \frac{\tilde{\sigma}_\theta}{r} + \rho \omega^2 r \right) dV = 0 \quad (A)$$

Apply Eq. 5.4-7 with $l = 1$.

$$\int \tilde{N}^T \left[\frac{1}{r} \frac{d}{dr} (r \tilde{\sigma}_r) \right] dV = - \int \tilde{N}_{,r}^T \tilde{\sigma}_r dV + \int \tilde{N}^T \tilde{\sigma}_r dS$$

Last term vanishes, as $\sigma_r = 0$ @ $r = r_i$ & $r = r_o$.

(A) becomes

$$\int_{r_i}^{r_o} \left[\tilde{N}_{,r}^T \quad \frac{1}{r} \tilde{N}^T \right] \underbrace{\begin{Bmatrix} \tilde{\sigma}_r \\ \tilde{\sigma}_\theta \end{Bmatrix}}_{\{ \underline{\sigma} \}} 2\pi r dr = \int_{r_i}^{r_o} \tilde{N}^T \rho \omega^2 r (2\pi r) dr$$

$$\begin{Bmatrix} \tilde{\sigma}_r \\ \tilde{\sigma}_\theta \end{Bmatrix} = \frac{E}{1-\nu^2} \begin{bmatrix} 1 & \nu \\ \nu & 1 \end{bmatrix} \begin{Bmatrix} \tilde{\epsilon}_r \\ \tilde{\epsilon}_\theta \end{Bmatrix} = [\underline{E}] \begin{Bmatrix} \tilde{u}_{,r} \\ \tilde{u} \\ r \end{Bmatrix} = [\underline{E}] \begin{bmatrix} \tilde{N}_{,r} \\ \frac{1}{r} \tilde{N} \end{bmatrix} \{ \underline{d} \}$$

$$\int_{r_i}^{r_o} \left[\tilde{N}_{,r}^T \quad \frac{1}{r} \tilde{N}^T \right] [\underline{E}] \begin{bmatrix} \tilde{N}_{,r} \\ \frac{1}{r} \tilde{N} \end{bmatrix} 2\pi r dr \{ \underline{d} \} = \{ \underline{f} \}$$

5.5-7

Multiply equilibrium eqs.

by weight function \tilde{N}^T and integrate.

$$\int \tilde{N}^T \left(\frac{1}{r} (r \tilde{\sigma}_r)_{,r} + \tilde{\gamma}_{r2,z} - \frac{\tilde{\sigma}_\theta}{r} \right) dV = 0 \quad (A)$$

$$\int \tilde{N}^T \left(\frac{1}{r} (r \tilde{\gamma}_{r2})_{,r} + \tilde{\sigma}_{z,z} \right) dV = 0 \quad (B)$$

Integrations by parts (e.g. Eq. 5.4-7):

$$\int \tilde{N}^T \left(\frac{1}{r} (r \tilde{\sigma}_r)_{,r} \right) dV = - \int \tilde{N}_{,r} \tilde{\sigma}_r dV + \int \tilde{N}^T \tilde{\sigma}_r n dS$$

$$\int \tilde{N}^T \tilde{\gamma}_{r2,z} dV = - \int \tilde{N}_{,z} \tilde{\gamma}_{r2} dV + \int \tilde{N}^T \tilde{\gamma}_{r2} n dS$$

$$\int \tilde{N}^T \left(\frac{1}{r} (r \tilde{\gamma}_{r2})_{,r} \right) dV = - \int \tilde{N}_{,r} \tilde{\gamma}_{r2} dV + \int \tilde{N}^T \tilde{\gamma}_{r2} n dS$$

$$\int \tilde{N}^T \tilde{\sigma}_{z,z} dV = - \int \tilde{N}_{,z} \tilde{\sigma}_z dV + \int \tilde{N}^T \tilde{\sigma}_z n dS$$

Now $l \tilde{\sigma}_r + n \tilde{\gamma}_{r2} = \tilde{\Phi}_r$ & $l \tilde{\gamma}_{r2} + n \tilde{\sigma}_z = \tilde{\Phi}_z$, so the two residual eqs. (A) & (B) become

$$\int \left[\begin{array}{cccc} \tilde{N}_{,r} & 0 & \frac{1}{r} \tilde{N}^T & \tilde{N}_{,z} \\ 0 & \tilde{N}_{,z} & 0 & \tilde{N}_{,r} \end{array} \right] \left\{ \begin{array}{c} \tilde{\sigma}_r \\ \tilde{\sigma}_z \\ \tilde{\gamma}_{r2} \end{array} \right\} dV =$$

$$\int \left[\begin{array}{cc} \tilde{N}^T & 0 \\ 0 & \tilde{N}^T \end{array} \right] \left\{ \begin{array}{c} \tilde{\Phi}_r \\ \tilde{\Phi}_z \end{array} \right\} dS$$

Using conventional notation, this eq. is

$$\int [\underline{B}]^T \{ \tilde{\sigma} \} dV = \int [\underline{N}]^T \{ \tilde{\Phi} \} dS \quad (C)$$

$$\text{R.t. } \{ \tilde{\sigma} \} = [\underline{E}] \{ \tilde{\epsilon} \} = [\underline{E}] [\underline{B}] \{ \underline{d} \} \quad (D)$$

where, with $\{ \underline{d} \} = [u_1, u_2, \dots, w_1, w_2, \dots]^T$,

$$\{ \tilde{\epsilon} \} = \left\{ \begin{array}{c} \tilde{\epsilon}_r \\ \tilde{\epsilon}_z \\ \tilde{\gamma}_{r2} \end{array} \right\} = \left[\begin{array}{cc} \tilde{N}_{,r} & 0 \\ 0 & \tilde{N}_{,z} \\ \frac{1}{r} \tilde{N} & 0 \\ \tilde{N}_{,z} & \tilde{N}_{,r} \end{array} \right] \{ \underline{d} \}$$

Eqs. (C) & (D) yield the standard result:

$$\int [\underline{B}]^T [\underline{E}] [\underline{B}] dV \{ \underline{d} \} = \int [\underline{N}]^T \{ \tilde{\Phi} \} dS$$

5.6-1 Apply Eq. 5.6-9. Including all six d.o.f. of the two-el. model,

$$A \begin{bmatrix} -L/3E & -1/2 & -L/6E & 1/2 & 0 & 0 \\ -1/2 & 0 & -1/2 & 0 & 0 & 0 \\ -L/6E & -1/2 & -L/3E & 1/2 & 0 & 0 \\ 1/2 & 0 & 1/2 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} \begin{Bmatrix} \sigma_1 \\ u_1 \\ \sigma_2 \\ u_2 \\ \sigma_3 \\ u_3 \end{Bmatrix} +$$

$$A \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & -L/3E & -1/2 & -L/6E & 1/2 \\ 0 & 0 & -1/2 & 0 & -1/2 & 0 \\ 0 & 0 & -L/6E & -1/2 & -L/3E & 1/2 \\ 0 & 0 & 1/2 & 0 & 1/2 & 0 \end{bmatrix} \begin{Bmatrix} \sigma_1 \\ u_1 \\ \sigma_2 \\ u_2 \\ \sigma_3 \\ u_3 \end{Bmatrix} = \begin{Bmatrix} \text{load} \\ \text{terms} \end{Bmatrix}$$

Combine. Discard rows & columns 2 and 5 to impose boundary conditions $u_1 = 0$ and $\sigma_3 = 0$. Include load terms $F_{q1} = cL/2$ and $F_{q2} = cL/2$ (as in Eq. 5.6-8). Thus

$$A \begin{bmatrix} -L/3E & -L/6E & 1/2 & 0 \\ -L/6E & -2L/3E & 0 & 1/2 \\ 1/2 & 0 & 0 & 0 \\ 0 & 1/2 & 0 & 0 \end{bmatrix} \begin{Bmatrix} \sigma_1 \\ \sigma_2 \\ u_1 \\ u_2 \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \\ cL/2 \\ cL/2 \end{Bmatrix}$$

Solution is $\begin{Bmatrix} \sigma_1 \\ \sigma_2 \\ u_2 \\ u_3 \end{Bmatrix} = \begin{Bmatrix} cL/A \\ cL/A \\ cL^2/AE \\ 5cL^2/3AE \end{Bmatrix}$ ✓
 ✓
 ✓
 ← exact is $\frac{3cL^2}{2AE}$

5.6-2

Governing eqs. are $v_{,xx} - \frac{M}{EI} = 0$ and $M_{,xx} - q = 0$

Assume, for element fields, $\tilde{v} = \tilde{N}\tilde{v}_e$ and $\tilde{M} = \tilde{N}M_e$

First eq.: $\int_0^L \tilde{N}^T (\tilde{v}_{,xx} - \frac{\tilde{M}}{EI}) dx = 0$. Integrate 1st term by parts:

$$\int_0^L \tilde{N}^T \tilde{v}_{,xx} dx = \left[\tilde{N}^T \tilde{v}_{,x} \right]_0^L - \int_0^L \tilde{N}_{,x}^T \tilde{v}_{,x} dx \quad \text{Hence 1st eq. becomes}$$

$$- \underbrace{\int_0^L \tilde{N}_{,x}^T \tilde{N}_{,x} dx}_{\tilde{H}_{12}} \tilde{v}_e - \underbrace{\int_0^L \frac{1}{EI} \tilde{N}^T \tilde{N} dx}_{\tilde{H}_{11}} M_e = - \left[\tilde{N}^T \tilde{v}_{,x} \right]_0^L$$

↑ Cancels upon assembly of elements

Second eq.: $\int_0^L \tilde{N}^T (\tilde{M}_{,xx} - q) dx = 0$. Integrate 1st term by parts:

$$\int_0^L \tilde{N}^T \tilde{M}_{,xx} dx = \left[\tilde{N}^T \tilde{M}_{,x} \right]_0^L - \int_0^L \tilde{N}_{,x}^T \tilde{M}_{,x} dx \quad \text{Hence 2nd eq. becomes}$$

$$- \underbrace{\int_0^L \tilde{N}_{,x}^T \tilde{N}_{,x} dx}_{\tilde{H}_{12}} M_e = \underbrace{\int_0^L \tilde{N}^T q dx}_{\tilde{r}_q} - \left[\tilde{N}^T \tilde{M}_{,x} \right]_0^L$$

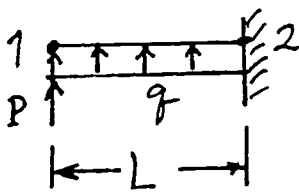
↑ Cancels upon assembly of els.

Put together: $\begin{bmatrix} \tilde{H}_{11} & \tilde{H}_{12} \\ \tilde{H}_{12} & 0 \end{bmatrix} \begin{Bmatrix} M_e \\ v_e \end{Bmatrix} = \begin{Bmatrix} 0 \\ -\tilde{r}_q \end{Bmatrix}$ in which, if $[N] = \begin{bmatrix} L-x & x \\ L & L \end{bmatrix}$,

$$[\tilde{H}_{11}] = \frac{L}{6EI} \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}, \quad [\tilde{H}_{12}] = \frac{1}{L} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$$

$$\text{hence } \begin{bmatrix} L/3EI & L/6EI & 1/L & -1/L \\ L/6EI & L/3EI & -1/L & 1/L \\ 1/L & -1/L & 0 & 0 \\ -1/L & 1/L & 0 & 0 \end{bmatrix} \begin{Bmatrix} M_1 \\ M_2 \\ v_1 \\ v_2 \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \\ -r_{q1} \\ -r_{q2} \end{Bmatrix}$$

Example: $M_1=0, v_2=0$, so



$$\begin{bmatrix} L/3EI & -1/L \\ -1/L & 0 \end{bmatrix} \begin{Bmatrix} M_2 \\ v_1 \end{Bmatrix} = \begin{Bmatrix} 0 \\ -P - qL/2 \end{Bmatrix}$$

$$\text{Gives } M_2 = PL + \frac{qL^2}{2}, \quad v_1 = \frac{PL^3}{3EI} + \frac{qL^4}{6EI}$$

Should be $qL^4/8EI$; other terms in M_2 and v_1 are exact.

5.6-3

$$\Pi = \int \left(\sigma_x \frac{du}{dx} - \frac{\sigma_x^2}{2E} - \frac{q}{A} u \right) A dx$$

In an element, $\sigma_x = \tilde{N} \sigma_e$
 $u = \tilde{N} u_e$

hence $\sigma_x^T = \sigma_e^T \tilde{N}^T$
 $u_{,x} = \tilde{N}_{,x} u_e$

$$\Pi = \int \left(\sigma_e^T \tilde{N}^T \tilde{N}_{,x} u_e - \frac{1}{2E} \sigma_e^T \tilde{N}^T \tilde{N} \sigma_e - u_e^T \tilde{N}^T \frac{q}{A} \right) A dx$$

$$\frac{\partial \Pi}{\partial \sigma_e} = \underbrace{\int \tilde{N}^T \tilde{N}_{,x} A dx}_{[k_{\sigma u}]} u_e - \underbrace{\int \tilde{N}^T \tilde{N} \frac{A}{E} dx}_{[k_{\sigma \sigma}]} \sigma_e$$

$$\frac{\partial \Pi}{\partial u_e} = \underbrace{\int \tilde{N}_{,x}^T \tilde{N} A dx}_{[k_{u \sigma}]} \sigma_e - \underbrace{\int \tilde{N}^T q dx}_{\{r_f\}}$$

Thus
$$\begin{bmatrix} -k_{\sigma \sigma} & k_{\sigma u} \\ k_{u \sigma} & 0 \end{bmatrix} \begin{Bmatrix} \sigma_e \\ u_e \end{Bmatrix} = \begin{Bmatrix} 0 \\ r_f \end{Bmatrix} \quad \checkmark$$